### Research Gaps in DDFA

## Robert C. Bedick DOE-NETL

**Deactivation and Decommissioning Focus Area** 

Industry Partnerships for Environmental Science and Technology Conference

DOE-NETL

Morgantown, WV October 30 -November 1, 2001





### **Presentation Outline**

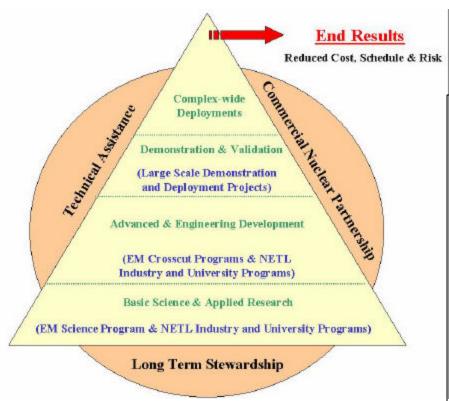
- DDFA Mission and Programs
- National Research Council Report for DDFA
- Current Projects
- Concluding Remarks



### The DDFA Mission

"There are strong safety and economic incentives for developing and using innovative D&D technologies that may be achieved through scientific research. The long time frame for completing D&D (50 years or more) allows for substantive research to be completed and applied."

National Research Council 2001



#### **DDFA** mission statement:

Provide technological solutions which reduce the cost, risk and schedule to deactivate and decommission DOE's radiologically contaminated excess facilities

# National Research Council (NRC) Report for DDFA

- Identified 4 principle areas for research investment:
  - 1) characterization of contaminated materials
    - especially volumetrically contaminated concrete and metals
  - 2) decontamination of equipment and facilities
  - 3) remote intelligent systems to improve worker safety
  - 4) end state definition for facility D&D
- The first 3 areas were directly addressed by the 10 topic areas within the DDFA applied research solicitation



## **Applied R&D Topic Areas**

Need Description	Applied Research Projects	Basic Research Projects
Improvements to	4	3
Characterization Technology		
New Systems for Long Term	1	0
Surveillance and Maintenance		
New Characterization	0	0
Techniques for Pipes, Ducts,		
Tanks, etc.		
Next Generation	4	6
Decontamination Technology		
for Metals & Concrete		
Improved Size-Reduction and	3	0
Demolition Technologies		

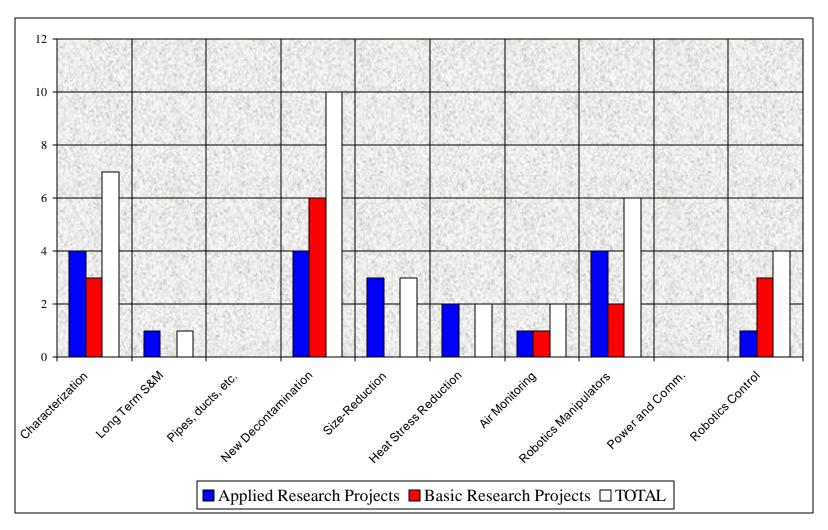


### **Applied R&D Topic Areas (continued)**

Need Description	Applied Research Projects	Basic Research Projects
Technologies for Worker Heat	2	0
Stress Reduction		
Improved Air Monitoring	1	1
Technology and		
Contamination Control		
Advanced Manipulators and	4	2
End Effectors		
Tetherless Power and	0	0
Communications Systems		
Sensor- based Manipulator	1	3
Control Systems		



### **Applied R&D Topics (continued)**







Carnegie Mellon BOA: Asbestos Pipe-Insulation Removal System



RedZone Robotics Houdini



3M Empore<sup>TM</sup>
Membrane Separation
Technology

## **Concluding Remarks**



Carnegie Mellon Robotics Rosie



Science & Engineering Associates

